## **Bayesian Community Detection**

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#### **Outline**

The Stochastic Block Model

The Bayesian estimator

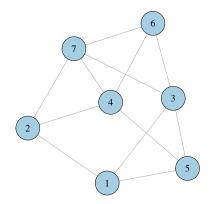
Example

#### The Stochastic Block Model

Undirected graph without self-loops, of *n* nodes.

Observe adjacency matrix A:

$$A = \left(\begin{array}{ccccccc} 0 & 1 & 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 & 0 & 1 & 0 \end{array}\right)$$



#### The Stochastic Block Model

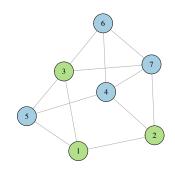
K classes.

Latent class labels:  $Z = (Z_1, ..., Z_n), Z_i \in \{1, ..., K\}$ . For i < j:

$$\mathbb{P}(A_{ij}=1\mid Z_i=a,Z_j=b)=P_{ab}$$

where P is a symmetric  $K \times K$ -matrix of probabilities.

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The  $Z_i$  are generated according to

$$\mathbb{P}(Z_i=a)=\pi_a,$$

for some  $\pi \in \mathbb{R}^K$  such that  $\sum_{a=1}^K \pi_a = 1$ .

Goal: recovery of labels.

### Other approaches

- ► Spectral clustering (e.g. Rohe, Chatterjee and Yu (2011), Jin (2015), Sarkar and Bickel (2015), Lei and Rinaldo (2015))
- ► Largest Gaps algorithm (Channarond, Daudin and Robin (2012))
- ► Newman-Girvan modularity (e.g. Newman and Girvan (2004))
- ► Likelihood modularity (Bickel and Chen (2009), Zhao, Levina and Zhu (2012))

Bayesian approach (e.g. Nowicki and Snijders (2001), McDaid et al. (2013)): theoretical results lacking.

## The Bayesian modularity

The prior on the vector of class labels *z*:

$$\pi \sim \text{Dir}\left(\frac{K+3}{2}, \dots, \frac{K+3}{2}\right)$$

$$n_1, \dots, n_K \mid \pi \sim \text{Multinomial}(n, \pi)$$

Given  $n_1, \ldots, n_K$ , the labelling z is then drawn as a random ordering of the following sequence:

$$\underbrace{1,\ldots,1}_{n_1},\underbrace{2,\ldots,2}_{n_2},\ldots,\underbrace{K,\ldots,K}_{n_K}.$$

Independently:

$$P_{ab} \sim \operatorname{Beta}\left(\frac{1}{2}, \frac{1}{2}\right), \quad 1 \leq a \leq b \leq K.$$

### The Bayesian modularity

Use the posterior mode as estimator of Z.

Let

```
n_a(z) = number of nodes in class a;

n_{ab}(z) = maximum possible number of edges

between classes a and b;

O_{ab}(z) = observed number of edges

between classes a and b.
```

## The Bayesian modularity

The Bayesian modularity is given by

$$Q_{B}(z) = \frac{1}{n^{2}} \sum_{a \le b} \log B(O_{ab}(z) + \frac{1}{2}, n_{ab}(z) - O_{ab}(z) + \frac{1}{2})$$
$$+ \frac{1}{n^{2}} \sum_{a=1}^{K} \log \frac{\Gamma\left(n_{a}(z) + \frac{K+3}{2}\right)}{\Gamma(n_{a}(z) + 1)}.$$

The Bayesian MAP-estimator is:

$$\widehat{z} = \arg\max_{z} Q_{B}(z).$$

## Weak and strong consistency

An estimator is weakly consistent if the fraction of misclassified nodes goes to zero in probability.

An estimator is strongly consistent if the number of misclassified nodes goes to zero in probability.

## Strong consistency of the Bayesian modularity

#### Theorem [strong consistency]

If P is symmetric, every pair of rows of P is different, 0 < P < 1, and  $\pi > 0$ , then the MAP classifier  $\hat{z} = \arg\max_z Q_B(z)$  is strongly consistent if the expected degree is of larger order than  $(\log n)^2$ .

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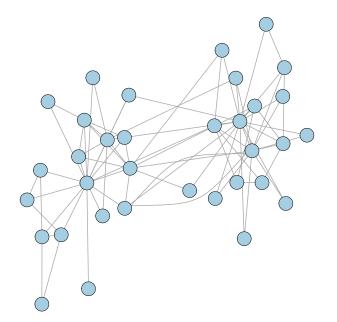
#### Full posterior useful for

- uncertainty quantification?
- estimating K?

## Implementation

- $\blacktriangleright$  McDaid et al. (2013): allocation sampler,  $\sim$  10.000 nodes
- ► Côme and Latouche (2014): greedy inference algorithm
- ▶ tabu search (Glover, 1989)

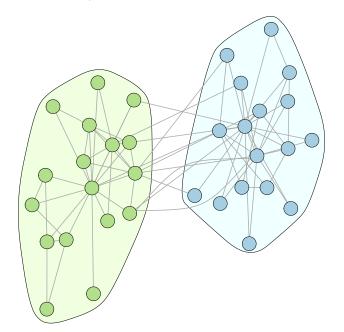
# Example: Zachary's karate club



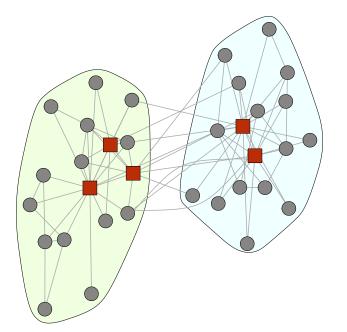
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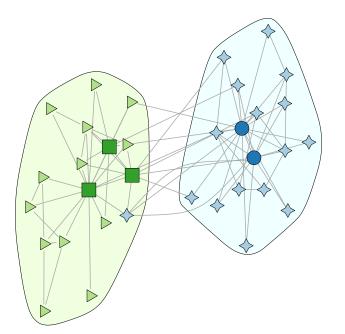
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# K = 2



# K = 4



#### **Conclusions**

- ► Strongly consistent community detection with a Bayesian approach is possible, provided the expected degree is of larger order than (log n)².
- Encourages further investigation into the full potential of the full posterior.

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